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Pulse Width Modulation Objective Questions With Answers ... Pulse Width Modulation or PWM is a common technique used to vary the width of the pulses in a pulse-train. PWM has many applications such as controlling servos and speed controllers, limiting the effective power of motors and LEDs.

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22) In different types of Pulse Width Modulation, a. Leading edge of the pulse is kept constant b. Tail edge of the pulse is kept constant c. Centre of the pulse is kept constant d. All of the above. ANSWER: (d) All of the above. 23) In pulse width modulation, a. Synchronization is not required between transmitter and receiver b.

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Answer Explanation. ANSWER: To remove noise.
Explanation: In pulse width modulation, the width of the carrier varies with the amplitude of the modulating signal at the time of sampling. In PWM signal reception, the received PWM signal is applied to the Schmitt trigger circuit.

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20) The digital modulation technique in which the

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step size is varied according to the variation in the slope of the input is called. a. Delta modulation b. PCM c. Adaptive delta modulation d. PAM. ANSWER: (c) Adaptive delta modulation. 21) The digital modulation scheme in which the step size is not fixed is. a. Delta modulation b.

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QUESTIONS AND ANSWERS ON PULSE CODE MODULATION. Q.1. Define Pulse Code Modulation?
Ans. Pulse Code Modulation is a type of pulse modulation like Pulse Amplitude Modulation , Pulse Width Modulation , or Pulse Position Modulation but there is an important difference between them Pulse Amplitude Modulation, Pulse Width Modulation, Pulse Position Modulation are analog pulse modulation system where as Pulse Code Modulation is a digital

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modulation system.

~~QUESTIONS AND ANSWERS ON PULSE CODE MODULATION~~

Firstly, make the connections as described below. Connect the positive leg of LED which is the longer leg to the digital pin 6 of Arduino. Then connect the 220 ohm resistor to the negative leg of LED and connect the other end of resistor to the ground pin of Arduino. Read More: [Interfacing LED with Arduino](#).

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The duty cycle is the percentage of the ratio of the pulse width of the signal to the total period (T). Here's

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a formula to further simplify things: % Duty cycle = (TON/ (TON + TOFF)) For example, if a pulse with a period of 20ms remains ON (high) for 4ms, its duty cycle will be. $\text{Duty cycle (D)} = 4\text{ms} / 20\text{ms} = 20\%$.

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