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To be available freely on-line at the link above, and is perfectly adequate for the course; We will refer to this text as MLS (the initials of the authors last names). While the course topics will follow the text subjects, additional material not in the text will often

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ME115 2016 - Robotics

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LECTURE 1 • Introduction and
Background • Open-loop Vs
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- Representation of Systems
- System Classification
- Laplace Transform
- Transfer Function
- Introduction and Background

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